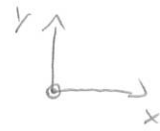


(6.1)

Repr. [2]: $R(\phi) = \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix}$



$$S = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \text{car } \begin{matrix} x \rightarrow x \\ y \rightarrow -y \end{matrix}$$

$$\begin{aligned} S R(\phi) S^{-1} &= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \\ &= \begin{pmatrix} \cos \phi & -\sin \phi \\ -\sin \phi & -\cos \phi \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} \cos \phi & \sin \phi \\ -\sin \phi & \cos \phi \end{pmatrix} = R(-\phi) \end{aligned}$$

$\Rightarrow O(2)$ pas abélien (Abélien $\Rightarrow S R S^{-1} = S S^{-1} R = R$)

Irreps de $SO(2)$: $D^{(m)}(\phi) = e^{-im\phi}$, $m \in \mathbb{Z}$ $\Gamma D^V = D^{(1)} \oplus D^{(-1)}$

$$\Rightarrow S D^{(m)}(\phi) S^{-1} = D^{(m)}(-\phi) = e^{im\phi} = D^{(-m)}(\phi) \quad \leadsto D^{(m)}(\phi) \text{ pas fermé pour } m \neq 0$$

\Rightarrow Irreps de $O(2)$: $D^{(m)}(\phi) \oplus D^{(-m)}(\phi)$ pour $m \neq 0$

$$D^{|m|}(\phi) = D^{(m)}(\phi) \oplus D^{(-m)}(\phi) = \begin{pmatrix} e^{im\phi} & 0 \\ 0 & e^{-im\phi} \end{pmatrix}$$

$$D^{|m|}(S) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Caractères:

$$\chi^{|m|}(\phi) = 2 \cos m\phi, \quad \chi^{|m|}(S) = 0$$

Pour $m=0$: $D^{(0)}(\phi) = 1$ reste irréductible

avec deux possibilités pour S : $S=1$ ou $S=-1$

$$\chi^{A_+}(\phi) = 1, \quad \chi^{A_+}(S) = 1 \quad ; \text{repr. triviale}$$

$$\chi^{A_-}(\phi) = 1, \quad \chi^{A_-}(S) = -1$$

$$D^{1ml}(\varphi) = \begin{pmatrix} e^{im\varphi} & 0 \\ 0 & e^{-im\varphi} \end{pmatrix}$$

$$\begin{pmatrix} x'+iy' \\ x'-iy' \end{pmatrix} = D^{1ml}(\varphi) \begin{pmatrix} x+iy \\ x-iy \end{pmatrix}$$

$$x'+iy' = e^{im\varphi} (x+iy)$$

$$x'-iy' = e^{-im\varphi} (x-iy)$$

$$\begin{aligned} 2x' &= (e^{im\varphi} + e^{-im\varphi})x + (e^{im\varphi} - e^{-im\varphi})iy \\ &= 2\cos m\varphi x - 2\sin m\varphi y \end{aligned}$$

$$2iy' = (e^{im\varphi} - e^{-im\varphi})x + (e^{im\varphi} + e^{-im\varphi})iy$$

$$x' = \cos m\varphi x - \sin m\varphi y$$

$$y' = \sin m\varphi x + \cos m\varphi y$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = D^{1ml}(\varphi) \begin{pmatrix} x \\ y \end{pmatrix}, \quad D^{1ml}(\varphi) = \begin{pmatrix} \cos m\varphi & -\sin m\varphi \\ \sin m\varphi & \cos m\varphi \end{pmatrix}$$

$$\begin{pmatrix} x'+iy' \\ x'-iy' \end{pmatrix} = D^{1ml}(S) \begin{pmatrix} x+iy \\ x-iy \end{pmatrix}, \quad D^{1ml}(S) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$x'+iy' = x-iy$$

$$x'-iy' = x+iy$$

$$2x' = 2x$$

$$x' = x$$

$$2iy' = -2iy$$

$$y' = -y$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = D^{1ml}(S) \begin{pmatrix} x \\ y \end{pmatrix}, \quad D^{1ml}(S) = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

(6.2)

Angles d'Euler: $R(\varphi, \theta, \psi) = e^{-iX_3''\varphi} e^{-iX_2'\theta} e^{-iX_3\varphi}$
↑ axe en direction (θ, φ)

$S R_{\hat{n}}(\alpha) S^{-1} = R_{\hat{n}'}(\alpha)$ avec $\hat{n}' = S \hat{n}$
Car première rotation autour l'axe \hat{e}_2' ne change pas l'axe \hat{e}_2'

$\Rightarrow e^{iX_3''\varphi} = e^{-iX_2'\theta} e^{-iX_3\varphi} e^{iX_2'\theta}$

$\Rightarrow R(\varphi, \theta, \psi) = e^{-iX_2'\theta} e^{-iX_3(\varphi+\psi)}$

Aussi: $e^{-iX_2'\theta} = e^{-iX_3\varphi} e^{-iX_2\theta} e^{iX_3\varphi}$

$\Rightarrow R(\varphi, \theta, \psi) = e^{-iX_3\varphi} e^{-iX_2\theta} e^{-iX_3\psi}$

Forme standard pour la tabulation des matrices de rotation $D^{(j)}$:

$D_{m'm}^{(j)}(\varphi, \theta, \psi) = e^{-im'\varphi} D_{m'm}^{(j)}(R_2(\theta)) e^{-im\psi}$

Seule partie non-triviale:

$d_{m'm}^{(j)}(\theta) = D_{m'm}^{(j)}(R_2(\theta)) \quad (j=0, 1/2, 1, 3/2, 2, \dots)$

(6.3)

$X_2 = \frac{1}{2} G_2, G_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, G_2^2 = \mathbb{1}$

$d^{1/2}(\theta) = e^{-iX_2\theta} = e^{-iG_2\frac{\theta}{2}} = \mathbb{1} \cos \frac{\theta}{2} - iG_2 \sin \frac{\theta}{2}$

$$\begin{aligned} \int e^{-iG_2 x} &= 1 - iG_2 x - \frac{x^2}{2!} + iG_2 \frac{x^3}{3!} + \frac{x^4}{4!} \pm \dots \\ &= \cos x - iG_2 \sin x, \quad x = \frac{\theta}{2} \end{aligned}$$

$\Rightarrow d^{1/2}(\theta) = \begin{pmatrix} \cos \frac{\theta}{2} & 0 \\ 0 & \cos \frac{\theta}{2} \end{pmatrix} + \begin{pmatrix} 0 & -\sin \frac{\theta}{2} \\ \sin \frac{\theta}{2} & 0 \end{pmatrix}$
 $= \begin{pmatrix} \cos \theta/2 & -\sin \theta/2 \\ \sin \theta/2 & \cos \theta/2 \end{pmatrix}$

(6.4)

$$\text{Cours: } |j m\rangle = \sum_{m_1 m_2} C^{*}(\dots) \langle m_1 m_2 | j m \rangle |m_1 m_2\rangle$$

$$D_{m' m}^{(j)}(R) \equiv \langle j m' | U(R) | j m \rangle$$

$$= \sum_{m_1'} \sum_{m_1} C(j_1 j_2 j; m_1' m_1 - m_1' m_1) C^*(j_1 j_2 j; m_1 m - m_1 m) D_{m_1' m_1}^{(j_1)}(R) D_{m_1 m_2}^{(j_2)}(R)$$

$$j_1 = j_2 = \frac{1}{2}$$

$$j = 1$$

$$m_1 m_1' = -j_1 \dots j_1$$

$$m_2 m_2' = -j_2 \dots j_2$$

$$R = R_z(\theta) : d_{m' m}^j(\theta) \equiv D_{m' m}^j(R_z(\theta)) \quad ; \quad m_1 m_1' = -j_1 \dots j_1$$

$$d_{m' m}^1(\theta) = \sum_{m_1'} \sum_{m_1} C\left(\frac{1}{2} \frac{1}{2} 1; m_1' \overbrace{m_1 - m_1'}^{m_2'} m_1\right) C^*\left(\frac{1}{2} \frac{1}{2} 1; m_1 \overbrace{m - m_1}^{m_2} m\right) d_{m_1' m_1}^{1/2}(\theta) d_{m_1 m_2}^{1/2}(\theta)$$

$$d_{11}^1, d_{10}^1, d_{1-1}^1 \quad ; \quad d_{01}^1, d_{00}^1, d_{0-1}^1 \quad ; \quad d_{-11}^1, d_{-10}^1, d_{-1-1}^1$$

$$C\left(\frac{1}{2} \frac{1}{2} 1; \frac{1}{2} \frac{1}{2} 1\right) = C\left(\frac{1}{2} \frac{1}{2} 1; -\frac{1}{2} -\frac{1}{2} -1\right) = 1$$

$$C\left(\frac{1}{2} \frac{1}{2} 1; \frac{1}{2} -\frac{1}{2} 0\right) = C\left(\frac{1}{2} \frac{1}{2} 1; -\frac{1}{2} \frac{1}{2} 0\right) = \frac{1}{\sqrt{2}}$$

$$d_{11}^1(\theta) = \left[d_{\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}}(\theta) \right]^2 = \cos^2 \frac{\theta}{2} = \frac{1}{2} (1 + \cos \theta)$$

$$d_{10}^1(\theta) = d_{\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}}(\theta) d_{\frac{1}{2} -\frac{1}{2}}^{\frac{1}{2}}(\theta) \frac{1}{\sqrt{2}} \cdot 2 = \sqrt{2} \cos \frac{\theta}{2} (-\sin \frac{\theta}{2}) = -\frac{1}{\sqrt{2}} \sin \theta$$

$$d_{1-1}^1(\theta) = d_{\frac{1}{2} -\frac{1}{2}}^{\frac{1}{2}}(\theta) d_{\frac{1}{2} -\frac{1}{2}}^{\frac{1}{2}}(\theta) = \sin^2 \frac{\theta}{2} = \frac{1}{2} (1 - \cos \theta)$$

skip

$$\left\{ \begin{aligned} d_{01}^1(\theta) &= d_{\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}}(\theta) d_{-\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}}(\theta) \frac{1}{\sqrt{2}} \cdot 2 = -d_{10}^1(\theta) = -d_{0-1}^1(\theta) \\ d_{00}^1(\theta) &= \frac{1}{2} \left(d_{\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}} d_{-\frac{1}{2} -\frac{1}{2}}^{\frac{1}{2}} + d_{\frac{1}{2} -\frac{1}{2}}^{\frac{1}{2}} d_{-\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}} \right) \cdot 2 = \cos^2 \frac{\theta}{2} - \sin^2 \frac{\theta}{2} = \cos \theta \\ d_{-11}^1(\theta) &= d_{1-1}^1(\theta) \\ d_{-10}^1(\theta) &= \frac{1}{\sqrt{2}} \left(d_{-\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}} d_{-\frac{1}{2} -\frac{1}{2}}^{\frac{1}{2}} + d_{-\frac{1}{2} -\frac{1}{2}}^{\frac{1}{2}} d_{-\frac{1}{2} \frac{1}{2}}^{\frac{1}{2}} \right) \cdot 2 = \sqrt{2} \sin \frac{\theta}{2} \cos \frac{\theta}{2} = \frac{1}{\sqrt{2}} \sin \theta = -d_{10}^1(\theta) \\ d_{-1-1}^1 &= d_{11}^1(\theta) \end{aligned} \right.$$

$$d_{m'm}^1(\theta) = \begin{pmatrix} \frac{1}{2}(1+\cos\theta) & -\frac{1}{\sqrt{2}}\sin\theta & \frac{1}{2}(1-\cos\theta) \\ \frac{1}{\sqrt{2}}\sin\theta & \cos\theta & -\frac{1}{\sqrt{2}}\sin\theta \\ \frac{1}{2}(1-\cos\theta) & \frac{1}{\sqrt{2}}\sin\theta & \frac{1}{2}(1+\cos\theta) \end{pmatrix}$$

$$D^V(R_z(\theta)) = \begin{pmatrix} \cos\theta & 0 & \sin\theta \\ 0 & 1 & 0 \\ -\sin\theta & 0 & \cos\theta \end{pmatrix} = R_{ij}(\theta) \quad ; \quad x_i' = R_{ij} x_j$$

$$x' = c_\theta x + s_\theta z$$

$$y' = y$$

$$z' = -s_\theta x + c_\theta z$$

$$\begin{aligned} x' + iy' &= s_\theta x + s_\theta z + iy = c_\theta (x+iy) + (x+iy) + s_\theta z \\ &\quad - c_\theta iy - x \\ &= (1+\cos\theta)(x+iy) + s_\theta z - c_\theta iy - x \\ &= \frac{1}{2}(1+\cos\theta)(x+iy) + s_\theta z \\ &\quad + \underbrace{\frac{1}{2}(1+\cos\theta)(x+iy) - x - \cos\theta iy}_{-\frac{1}{2}(1-\cos\theta)x + \frac{1}{2}(1-\cos\theta)iy} \\ &= \frac{1}{2}(1+\cos\theta)(x+iy) + s_\theta z - \frac{1}{2}(1-\cos\theta)(x-iy) \\ -\frac{1}{\sqrt{2}}(x'+iy') &= \frac{1}{2}(1+\cos\theta)\left[-\frac{x+iy}{\sqrt{2}}\right] - \frac{1}{\sqrt{2}}\sin\theta z + \frac{1}{2}(1-\cos\theta)\frac{x-iy}{\sqrt{2}} \end{aligned}$$

Similaire pour les autres lignes.

(6.5)

$$\langle j m' | \vec{J}_M | j m \rangle = C(1 j j | M m m') \langle j || \vec{J} || j \rangle$$

$$\langle j || \vec{J} || j \rangle \stackrel{!}{=} \sqrt{j(j+1)}$$

Prendre $m'=j$, $M=0 \rightsquigarrow \vec{J}_0 = \vec{J}_z$

$j \otimes 1$:

$$| j j \rangle = \alpha | j j \rangle_{10} + \beta | j j-1 \rangle_{11}$$

$$\begin{aligned} \vec{J}_+ | j j \rangle = 0 &= \alpha \sqrt{2} | j j \rangle_{11} \\ &+ \beta \sqrt{2j} | j j \rangle_{11} \end{aligned}$$

$$\Rightarrow \alpha + \beta \sqrt{j} = 0$$

$$\Leftrightarrow \beta = -\frac{\alpha}{\sqrt{j}}$$

$$\langle j j | j j \rangle = 1 \Leftrightarrow \alpha^2 + \beta^2 = 1 = \alpha^2 + \frac{\alpha^2}{j} \Leftrightarrow \alpha = \frac{\sqrt{j}}{\sqrt{j+1}} \Rightarrow \beta = -\frac{1}{\sqrt{j+1}}$$

$$\Rightarrow | j j \rangle = \left(\frac{\sqrt{j}}{\sqrt{j+1}} | j j \rangle_{10} - | j j-1 \rangle_{11} \right) \frac{1}{\sqrt{j+1}}$$

$$| j j \rangle = \sum_{\substack{m_1 m_2 \\ (m_1+m_2=j)}} \underbrace{\langle 1 m_1, j m_2 | j j \rangle}_{C(1 j j | m_1 m_2 j)} | 1 m_1 \rangle | j m_2 \rangle$$

$$\Rightarrow C(1 j j | 0 j j) = \frac{\sqrt{j}}{\sqrt{j+1}}$$

$$C(1 j j | 1 j-1 j) = -\frac{1}{\sqrt{j+1}}$$

$$M=0: \langle j j | \vec{J}_z | j j \rangle = j = \underbrace{C(1 j j | 0 j j)}_{\frac{\sqrt{j}}{\sqrt{j+1}}} \langle j || \vec{J} || j \rangle$$

$$\Rightarrow \boxed{\langle j || \vec{J} || j \rangle = \sqrt{j(j+1)}}$$

Alternativement :

$$M=1 : \quad \vec{r}_{j+1} = -(\vec{r}_1 + i\vec{r}_2) / \sqrt{2} = -\frac{1}{\sqrt{2}} \vec{r}_+$$

$$\begin{aligned} \langle j | \vec{r}_1 | j-1 \rangle &= \underbrace{C(1 \ j \ j \ j-1 \ j-1 \ j)}_{= -\frac{1}{\sqrt{j+1}}} \langle j || \vec{r} || j \rangle \\ &\parallel \\ -\frac{1}{\sqrt{2}} \sqrt{2j} \underbrace{\langle j | j | j \rangle}_{=1} & \qquad \vec{r}_+ | j j-1 \rangle = \sqrt{2j} | j j \rangle \end{aligned}$$

$$-\sqrt{j} = -\frac{1}{\sqrt{j+1}} \langle j || \vec{r} || j \rangle$$

$$= \boxed{\langle j || \vec{r} || j \rangle = \sqrt{j(j+1)}} \quad \checkmark \quad \text{même résultat}$$